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► To cite this version:

Eloïse Grossiord, Benoît Naegel, Hugues Talbot, Nicolas Passat, Michel Meignan, et al.. Shape-based analysis on component-graphs for multivalued image processing. Folle Journée de l'Imagerie Nantaise, 2016, Nantes, France. hal-01694958

HAL Id: hal-01694958 https://hal.univ-reims.fr/hal-01694958v1

Submitted on 8 Jan 2019

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SHAPE-BASED ANALYSIS ON COMPONENT-GRAPHS FOR MULTIVALUED IMAGE PROCESSING

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Introduction

The extension of mathematical morphology to multivalued images is an important issue. In this context, connected morphological operators based on hierarchical image models have been increasingly considered to provide efficient image segmentation and filtering tools in various application fields, e.g. (bio)medical imaging, astronomy or remote sensing.

We propose a preliminary study that describes how *component-graphs* (that extend the component-tree from a spectral point of view) and *shaping* (that extends the component-tree from a conceptual point of view) can be associated for the effective processing of multivalued images.

Previous works	Coupling component-graphs and shaping
Component-graphs [1]: Component-trees and multivalued images	We propose to associate the shaping and component-graph in a common framework for developing connected operators on multivalued images.

A (discrete) image $\mathcal{I}: \Omega \to \mathbb{V}$ (canonically equipped with an order relation \leq) can be modeled as a valued graph $(\mathcal{G}, \mathbb{V}, \mathcal{I})$. If (\mathbb{V}, \leq) is no longer a total order, the Hasse diagram associated to \mathcal{I} is no longer a tree:

- We extend the notion of connected component to valued con**nected component**: $\Theta = \bigcup_{v \in \mathbb{V}} \mathcal{C}[\mathcal{G}_v] \times \{v\}$
- We define an **order relation** \leq on Θ as

 $(X_1, v_1) \trianglelefteq (X_2, v_2) \Leftrightarrow \begin{cases} (X_1 \subset X_2) \lor \\ (X_1 = X_2 \land v_2 < v_1) \end{cases}$

- The component-graph CG of the valued graph $(G, \mathbb{V}, \mathcal{I})$ is the Hasse diagram of the partially ordered set (Θ, \leq) .
- Each node of CG can contain an **attribute value**, interpreted as a function $\mathcal{A}: \Theta \to \mathbb{R}$. Such enriched component-graph is also interpreted as a valued graph $(C\mathcal{G}, \mathbb{R}, \mathcal{A})$.



- We use **vertex-valued graphs** as a **unified formalism** to describe images, component-trees and component-graphs.
- The inner layer of shape-space filtering only **requires a graph**, not necessarily a tree.
- Generalization of the initial shaping paradigm: it can be used not only to build a "tree on a tree" but also a "tree on a graph".
- Any images can be processed via shape-based filtering :



Advantages of the framework

Figure 1: From left to right. First row: the Hasse diagram of the ordered set (\mathbb{V}, \leq) ; a multivalued image, viewed as a valued graph $(\mathcal{G}, \mathbb{V}, \mathcal{I})$ where \mathcal{G} is a part of \mathbb{Z}^2 equipped with the standard 4-adjacency relation; the component-graph \mathcal{CG} associated to $(\mathcal{G}, \mathbb{V}, \mathcal{I})$; a simplified version of the component-graph. Second and third rows: thresholded images obtained from the initial image. Each (valued) connected component is represented by a letter: A, B, C, etc. Note: A is the support of the figure (the background).

Shaping: Anti-extensive filtering in the shape-space

We consider the paradigm of **shapings**, proposed by Xu et al. [2], to extend the filtering capabilities of tree-based representation to **non-monotonic** attributes.

- Avoids the complex selection of nodes directly in CG.
- Extends the initial shaping approach to multivalued images.
- Inherits the good properties of shape-space filtering from increasing attributes: real-time and interactive node selection at higher semantic level.

Application to PET/CT image filtering

Illustrative proof of concept: We illustrate the potential usefulness of this framework by filtering coupled PET and CT images. The criterion considered for filtering is the compactness factor [3], defined as the ratio between the extremal eigenvalues of the matrix of inertia.







- The shaping framework consists of using a two-layer componenttree, i.e. a tree on a tree, that transforms any attribute into a monotonic one. This allows us to embed additional information. In particular it facilitates user interaction and real-time thresholdbased node selection.
- The first tree is the component-tree of the image: it models its successive binary level-sets. The second is the component-tree of this first tree, considered as an image whose points are the nodes, while intensities correspond to attribute values.
- Limited use to grey-level images considering a tree as intermediate data-structure.

Figure 2: From left to right: CT; PET + ground truth in purple; multivalued shape-based filtering visualized in the PET value space.

References

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