

Colour image filtering with component-graphs

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Motivation



Input image



Result

Problematic

How to filter a colour image without altering its contours?

Outline

- 1 Connected filters
- 2 Component-tree
- 3 Component-graph: a new structure
- 4 Colour image filtering with component-graphs
- 5 Conclusion and perspectives

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Connected filters

Definition

- A filter is said *connected* if it acts by merging image flat-zones.
- A connected filter preserves the image contours: a contour is either entirely preserved or entirely removed.
- Designed in the field of mathematical morphology.

Applications

- Attribute filtering
- Object detection
- Segmentation

Connected filters

Image simplification



Input image



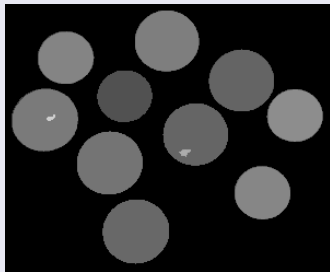
Area filtering

Connected filters

Shape detection



Input image



Compacity filtering

Connected filters

Segmentation



Input image

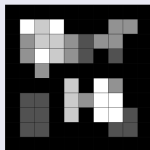


Segmentation

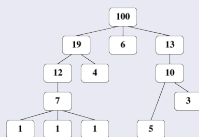
Connected filtering

Threshold decomposition

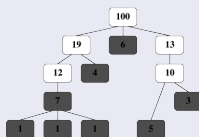
- A class of connected filters is based on image *threshold decomposition*.
- Efficient filters based on a tree-based image representation: the component-tree (or max-tree/min-tree).
- Limitation: applicable only on monovalued (grey-level) images.
- Purpose of this work: how to extend this scheme to colour images ?



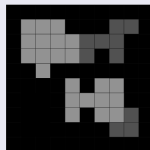
Input image



Component-tree



Tree filtering



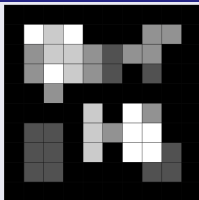
Result image

Outline

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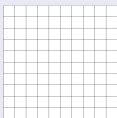
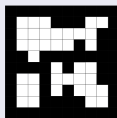
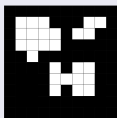
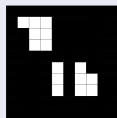
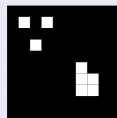
Component-tree (or max-tree) [Salembier98, Najman06]

Definition

 I

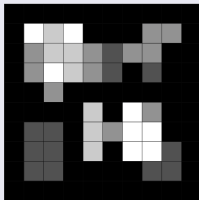
Threshold sets

- Image $I : \Omega \rightarrow V$.
- Threshold sets of $I : \lambda_v(I) = \{x \in \Omega \mid v \leq I(x)\}$
- Connected components of threshold sets: $\mathcal{C}[\lambda_v(I)]$
- Union of all components: $\Phi = \bigcup_{v \in V} \mathcal{C}[\lambda_v(I)]$

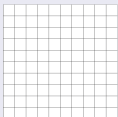
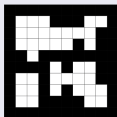
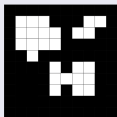
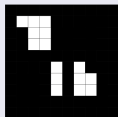
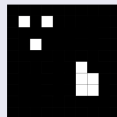
 $\lambda_0(I)$  $\lambda_1(I)$  $\lambda_2(I)$  $\lambda_3(I)$  $\lambda_4(I)$

Component-tree (or max-tree) [Salembier98, Najman06]

Definition

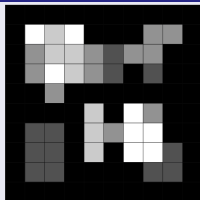
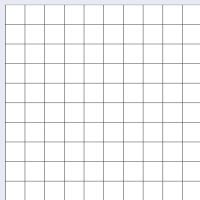
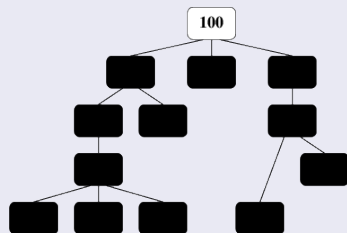
 I Component-tree \mathfrak{T} of I

- Connected component \rightarrow node
- Inclusion relation between two (different) connected components of successive threshold sets \rightarrow edge
- Equivalent to the Hasse diagram of the partially ordered set (Φ, \subseteq) .

 $\lambda_0(I)$  $\lambda_1(I)$  $\lambda_2(I)$  $\lambda_3(I)$  $\lambda_4(I)$

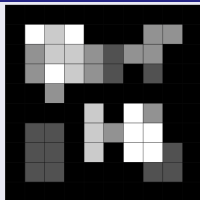
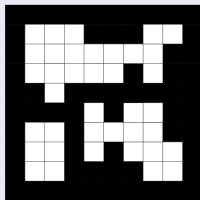
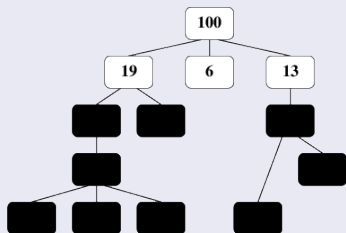
Component-tree (or max-tree) [Salembier98, Najman06]

Construction

 I  $\lambda_0(I)$ Component-tree of I : area attribute

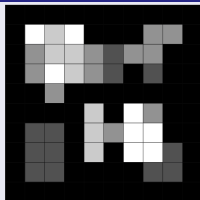
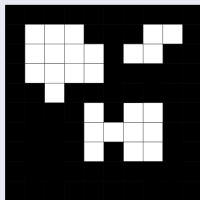
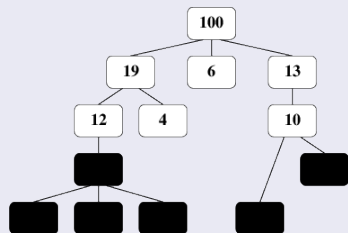
Component-tree (or max-tree) [Salembier98, Najman06]

Construction

 I  $\lambda_1(I)$ Component-tree of I : area attribute

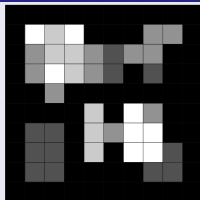
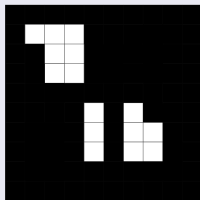
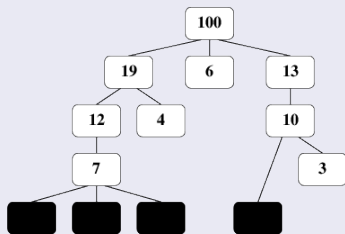
Component-tree (or max-tree) [Salembier98, Najman06]

Construction

 I  $\lambda_2(I)$ Component-tree of I : area attribute

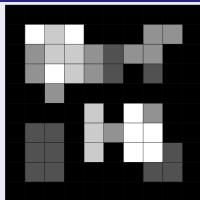
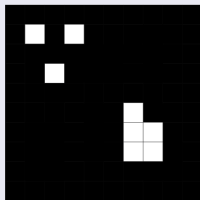
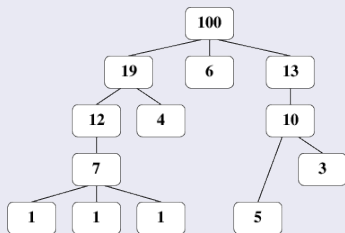
Component-tree (or max-tree) [Salembier98, Najman06]

Construction

 I  $\lambda_3(I)$ Component-tree of I : area attribute

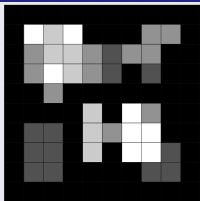
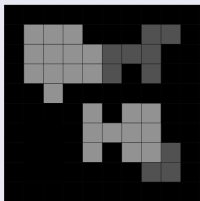
Component-tree (or max-tree) [Salembier98, Najman06]

Construction

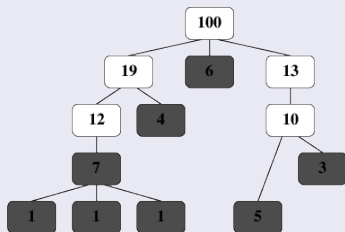
 I  $\lambda_4(I)$ Component-tree of I : area attribute

Component-tree (or max-tree) [Salembier98, Najman06]

Pruning

*I*

Filtered image (area filtering)



Tree pruning based on the criterion:

$$T(N) = \text{area} \geq 10$$

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Component-graph

Problematic

- How to extend threshold based approaches to multivalued images ?



Grey-level image



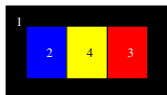
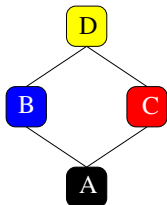
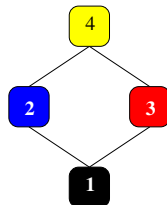
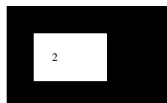
Threshold sets



Colour image



Component-graph

Input image I Hasse diagram of values V Component-graph of I Threshold sets of I : partial ordering

Component-graph

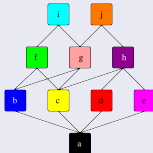
→ New structure introduced in [Passat2009, Naegel2013, Passat 2014]: the *component-graph*

Component-graph

Definition



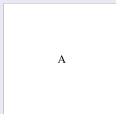
I



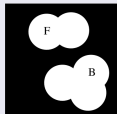
V

Set of valuated threshold components

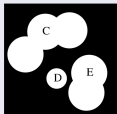
- $\Theta = \bigcup_{v \in V} \mathcal{C}[\lambda_v(I)] \times \{v\}$
- Ordering relation:
 $(X_1, v_1) \preceq (X_2, v_2) \Leftrightarrow (X_1 \subset X_2) \vee ((X_1 = X_2) \wedge (v_2 \leq v_1))$



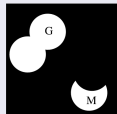
$\lambda_a(I)$



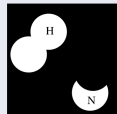
$\lambda_b(I)$



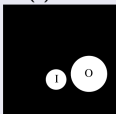
$\lambda_c(I)$



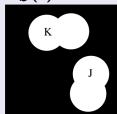
$\lambda_d(I)$



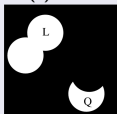
$\lambda_e(I)$



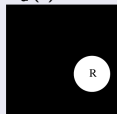
$\lambda_f(I)$



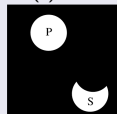
$\lambda_g(I)$



$\lambda_h(I)$



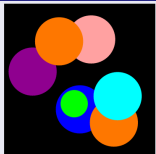
$\lambda_i(I)$



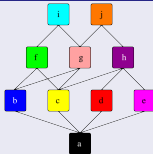
$\lambda_j(I)$

Component-graph

Definition



I



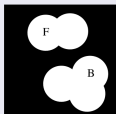
V

Component-graph

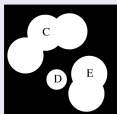
- The component-graph \mathfrak{G} of I is the Hasse diagram (Θ, \triangleleft) of the partially ordered set $(\Theta, \trianglelefteq)$.



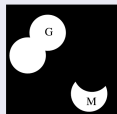
$\lambda_a(I)$



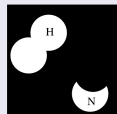
$\lambda_b(I)$



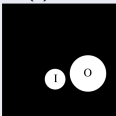
$\lambda_c(I)$



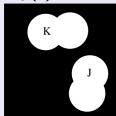
$\lambda_d(I)$



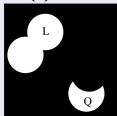
$\lambda_e(I)$



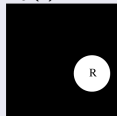
$\lambda_f(I)$



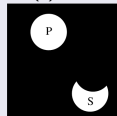
$\lambda_g(I)$



$\lambda_h(I)$



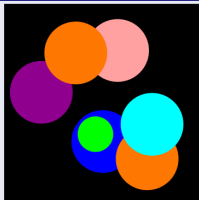
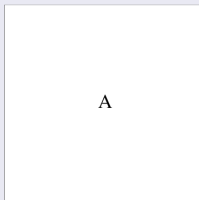
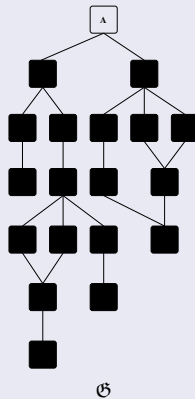
$\lambda_i(I)$



$\lambda_j(I)$

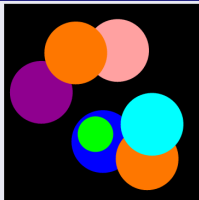
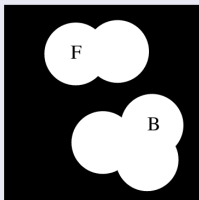
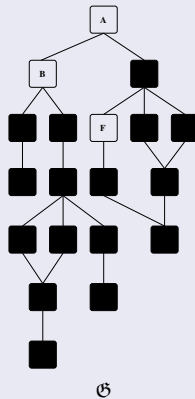
Component-graph

Definition


 I

 $\lambda_a(I)$


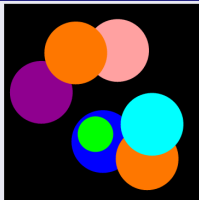
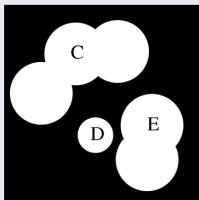
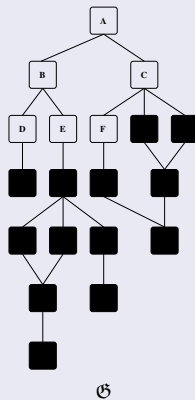
Component-graph

Definition


 I

 $\lambda_b(I)$


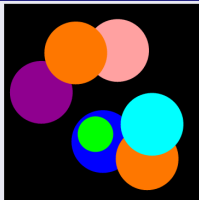
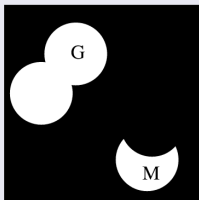
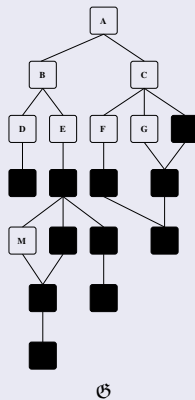
Component-graph

Definition


 I

 $\lambda_c(I)$

 \mathcal{G}

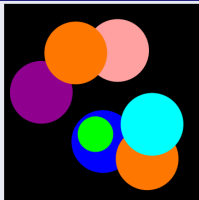
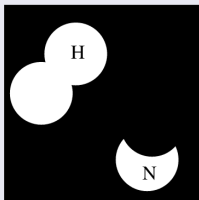
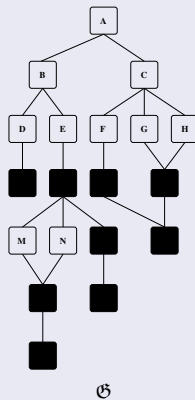
Component-graph

Definition


 I

 $\lambda_d(I)$


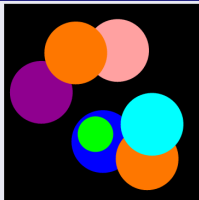
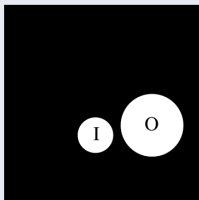
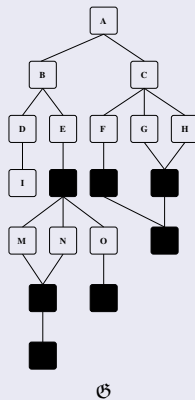
Component-graph

Definition


 I

 $\lambda_e(I)$


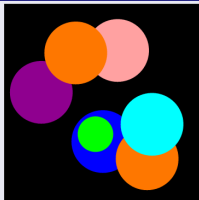
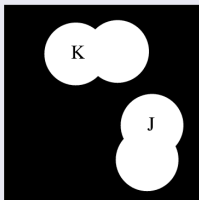
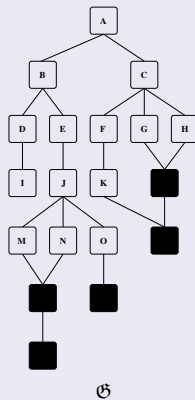
Component-graph

Definition


 I

 $\lambda_f(I)$


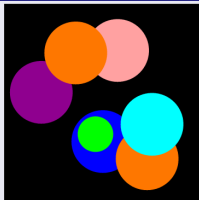
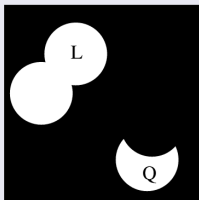
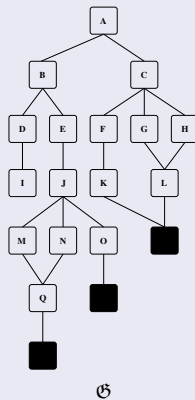
Component-graph

Definition


 I

 $\lambda_g(I)$


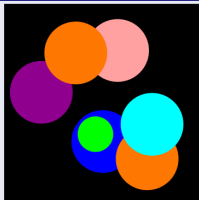
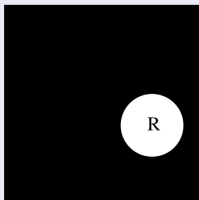
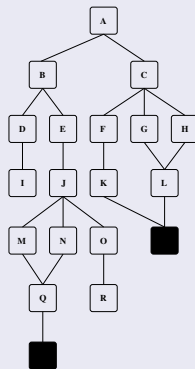
Component-graph

Definition


 I

 $\lambda_h(I)$

 \otimes

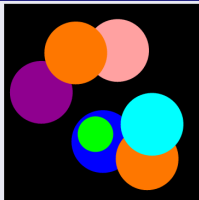
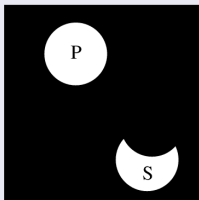
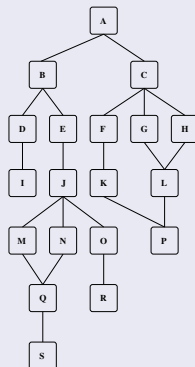
Component-graph

Definition


 I

 $\lambda_i(I)$

 \mathcal{G}

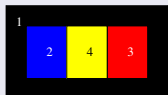
Component-graph

Definition

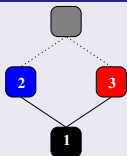

 I

 $\lambda_j(I)$

 \mathcal{G}

Component-graph pruning

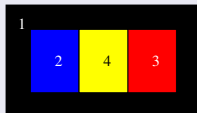
Reconstruction problem



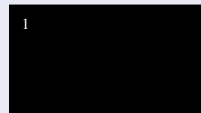
Input image



Pruned graph



Max policy



Min policy

- How to reconstruct an image from the pruned graph (since blue and red are not comparable)?

Outline

- 1 Connected filters
- 2 Component-tree
- 3 Component-graph: a new structure
- 4 Colour image filtering with component-graphs**
- 5 Conclusion and perspectives

Colour images

Space of values ?

- RGB space: $V = [0, 255]^3$
- HSV space
- ...

Ordering ?

- Marginal ordering: $V = [0, 255]^3$:
 $\forall v = (r, g, b), v' = (r', g', b') \in V, v \leq v' \Leftrightarrow r \leq r' \wedge g \leq g' \wedge b \leq b'$

Reconstruction policy

- Attribute filtering: remove all components that do not satisfy the criterion
- Min policy

Main strategy

Problems

- Algorithmic complexity $\mathcal{O}(N^2)$
- Space complexity (RGB space=16 millions of values)

Patch decomposition

- Attribute filtering: area, contrast (the “height” of component)
- Multithreading: decomposition of image in covering patches
- Each patch is filtered independantly

Adaptive filtering

- Pruning criterion is adapted for each patch (percentile based thresholding)

Colour images

Experimenting with RGB space



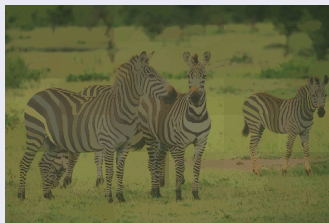
Original



Filtered (118 patches, $\alpha = 0.5$)



Original



Filtered (13 patches, $\alpha = 0.3$)

Colour images

Adaptive filtering



Original



Contrast filtering ($\lambda = 166$)



Adaptive area filtering ($\alpha = 0.5$)



Adapt. contrast filtering ($\alpha = 0.5$)

Colour images

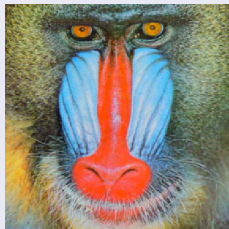
Experimenting with HSV space

- Partial ordering on [Saturation, Value] space closer from visual perception
- Component-graph pruning from [Saturation, Value] space
- The Hue value is unchanged

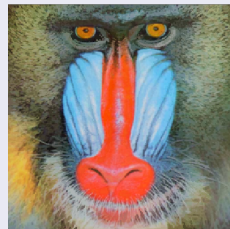
Colour images

Experimenting with HSV space

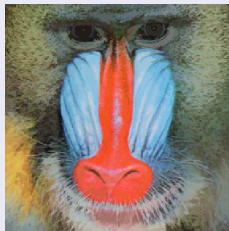
- Area attribute



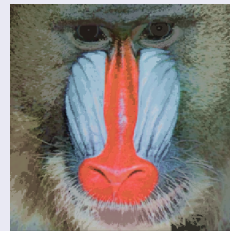
Original



$\alpha = 0.3$



$\alpha = 0.2$



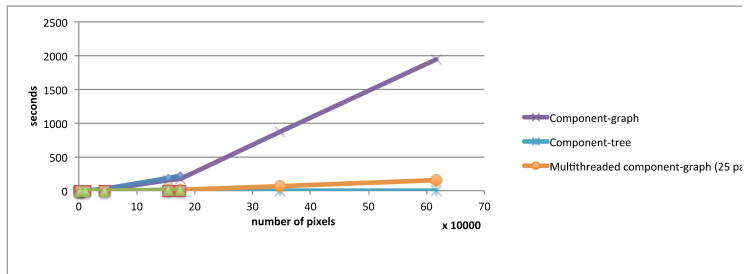
$\alpha = 0.1$

Colour images

Implementation

■ C++ / Qt

code.google.com/p/cgraph.



25 patches / threads - 4 cores.
In practice, $\mathcal{O}(N^{1.5})$ complexity.

Outline

- 1 Connected filters
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Conclusion et perspectives

Conclusion

- Component-graph : extending component-tree filtering paradigm on multivalued images.
- Practical applications on colour images based on patch decomposition and adaptive filtering

Perspectives

- Component-graph based segmentation.
- Addressing space and algorithm complexity: pruning the space of values.

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