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► **To cite this version:**

Hua Wong, Jean-Marc Crowet, Manuel Dauchez, Sylvie Ricard-Blum, Stéphanie Baud, et al.. Multiscale modelling of the extracellular matrix. Matrix Biology Plus, 2021, pp.100096. 10.1016/j.mbplus.2021.100096 . hal-03507342

HAL Id: hal-03507342

<https://hal.univ-reims.fr/hal-03507342v1>

Submitted on 22 Jul 2024

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MULTISCALE MODELLING OF THE EXTRACELLULAR MATRIX

2

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17

HIGHLIGHTS

- 19 • We introduce a set of theoretical modelling tools based on rigid body dynamics.
- 20 • Basement membrane components are modelled as articulated chains of rigid bodies.
- 21 • User-defined constraints can be used to investigate and modulate self-assembly.
- 22 • Sampled conformations can be exported to all-atom representation.

23

KEYWORDS

25 Extracellular matrix, modelling, simulation, rigid bodies, mesoscopic scale, basement
26 membrane

27

ABBREVIATIONS

29 CG, coarse-grained; Cryo-EM, cryogenic electron microscopy; DOF, degrees of freedom;
30 ECM, extracellular matrix; EGF, epidermal growth factor; FEM, finite element method; MD,
31 molecular dynamics; NC, non-collagenous; NMR, nuclear magnetic resonance; SAXS, small-
32 angle X-ray scattering.

33

34 **ABSTRACT**

35 The extracellular matrix is a complex three-dimensional network of molecules that provides
36 cells with a complex microenvironment. The major constituents of the extracellular matrix
37 such as collagen, elastin and associated proteins form supramolecular assemblies contributing
38 to its physicochemical properties and organization. The structure of proteins and their
39 supramolecular assemblies such as fibrils have been studied at the atomic level (e.g., by X-ray
40 crystallography, Nuclear Magnetic Resonance and cryo-Electron Microscopy) or at the
41 microscopic scale. However, many protein complexes are too large to be studied at the atomic
42 level and too small to be studied by microscopy. Most extracellular matrix components fall
43 into this intermediate scale, so-called the mesoscopic scale, preventing their detailed
44 characterization. Simulation and modelling are some of the few powerful and promising
45 approaches that can deepen our understanding of mesoscale systems. We have developed a set
46 of modelling tools to study the self-organization of the extracellular matrix and large motion
47 of macromolecules at the mesoscale level by taking advantage of the dynamics of articulated
48 rigid bodies as a mean to study a larger range of motions at the cost of atomic resolution.

49

50 **INTRODUCTION**

51 The extracellular matrix (ECM) is a three-dimensional network of proteins, proteoglycans and
52 glycosaminoglycans, which are found in different isoforms in tissues. Collagens, laminins,
53 fibronectin, thrombospondins, and proteoglycans belong to the core matrisome, whereas
54 ECM regulators, ECM-affiliated proteins, and secreted factors are referred to as matrisome-
55 associated proteins [1]. ECM components form insoluble supramolecular assemblies, which
56 provide tissues with mechanical properties, namely tensile strength for collagen fibrils, and
57 resistance to compression for proteoglycans. The organization of the ECM is tissue-specific,
58 and varies depending on the developmental stage, and the physio-pathological context.
59 Basement membranes are thin sheets of ECM, which underlie epithelial and endothelial cells,
60 compartmentalize tissues, and surrounds several cell types [2]. ECM molecular entities are of
61 various sizes, ranging from soluble, globular proteins of 10 nm in diameter or less to
62 macromolecules such as collagens which are several hundred nanometers in length and to
63 fibrils and fibers up to several μm -long [3,4]. Collagen IV molecules form tetramers and
64 dimers via their N- and C-termini respectively, which then self-assemble into a network
65 interacting with the other major components of basement membranes, namely perlecan,
66 laminins and nidogens.

67 It remains difficult to analyze full-length, multi-domain, ECM macromolecules by X-ray
68 crystallography or NMR and most structural data available at the atomic resolution are those
69 of individual domains which do not reflect the size and shape of the full-length proteins
70 deposited in the ECM. On the other hand, supramolecular assemblies such as fibrils can be
71 studied at the microscopic scale. However, several ECM large proteins (e.g., collagens,
72 laminins, and fibronectin) and protein complexes fall into an intermediate scale, the so-called
73 biological mesoscopic scale as defined in [5] that makes them difficult to observe directly at
74 atomic resolution. Indeed, experimental direct observations of ECM components in the range
75 of 10^{-7} m to 10^{-8} m are often at the lower limit of microscopy and upper limit of X-Ray
76 crystallography. While cryo-EM continues to increase in accuracy and resolution [6], proteins
77 with molecular weight lower than 50 kDa and biomolecules or complexes longer than 500 nm
78 (*i.e.*, the electron beam penetration limit) are still difficult to image [7].

79 All-atom molecular dynamics (MD) is an established method for studying the dynamics and
80 modifications of ECM-derived peptides. It does so by modelling each atom of a molecule as a
81 discrete point in space called particle, with a given set of parameters that are used to compute
82 the next state of the system at each timestep. It is a proven method to study the ectodomains
83 of membrane proteins [8] and/or protein domains [9–13]. It performs calculations on all the
84 atoms of the model and is especially useful for molecules up to 10-nm in length. In classical
85 MD, as the size of the system increases, so does the number of particles whose features
86 (coordinates, velocity, forces, energies) must be updated at each step of computation,
87 typically every 1-2 fs [14]. For example, the C-terminal non-collagenous (NC) domain 1 of
88 native trimeric collagen IV, a major component of basement membranes, is made up of ~5000
89 atoms. An all-atom model of collagen IV includes roughly 28 000 atoms without considering
90 any solvent or ions molecules. In addition to collagen IV, a model of a basement membrane
91 should comprise several collagen types (e.g., collagens IV and XVIII) as well as laminins and
92 the proteoglycan perlecan [15]. It should also include links to ECM cell surface receptors
93 such as integrins. The simulation of one atomistic model of a large biomolecule such as
94 collagen IV and a basement membrane made of a combination of the above macromolecules
95 would necessitate huge computational resources to perform calculations and store simulation
96 data even in the exascale computing (10^{18} calculations per second) and big data era. The
97 current record for an atomistic model (*i.e.*, the model of HIV-1 capsid) is the simulation of
98 over 64 million atoms for over 1 μ s, which required some of the largest existing
99 supercomputers [16].

100

101 For these systems and large ECM supramolecular assemblies (e.g., in the μm -range and
102 beyond such as collagen fibers), coarse-grained (CG) models, requiring fewer computational
103 resources, and discrete or finite elements methods (FEM) are used [17,18]. In contrast to fine-
104 grained models providing atomistic resolution), coarse-grained MD (CGMD) aims at
105 representing complex systems by a reduced number of subcomponents. CGMD clusters atoms
106 in larger beads which simulate the properties of the individual atoms they are made of. Using
107 the CGMD approach, the 5,000 atoms of the NC1 domain of collagen IV could be represented
108 by ten times fewer atoms, thus reducing the degrees of freedom (DOF) of the system and
109 allowing longer integration steps around 10-20 fs. This approach has been used successfully
110 to study collagen molecules [19] [20] and tropoelastin self-assembly into nascent fibrils [21].
111 At the nanoscale ($\leq 10^{-9}\text{m}$), water can be discretized as individual molecules. As we get closer
112 to the microscale, there are so many water molecules that they can be approximated into a
113 continuous medium (or *continuum*) without discrete separation. This concept of *continuum* is
114 referred to as implicit solvation and is also called *continuum* solvation in MD. While in
115 molecular dynamics, atoms position and velocity are updated at each time point according to
116 Newton's equation of motion, in rigid body dynamics, protein domains are considered as rigid
117 domains whose volumes never change or deform during the simulation [22].
118 In contrast with all-atom MD or CG simulations, FEM tools, such as OpenFOAM [23][24] or
119 ANSYS require the computing power of a desktop workstation but will only work at a scale
120 where matter can be considered a *continuum* and cannot predict the behavior of discrete atoms
121 [25] or sub-domains. Furthermore, FEM is well suited for large systems ranging from the
122 macroscale to the microscale from 1 m to 10^{-6} m.
123 We have developed a set of tools within the DURABIN project (Developing Utilities for
124 Nanometric Interactions in Biochemistry with Augmented Reality) [26] to help users without
125 expertise in modeling to build models of large macromolecules or multimolecular complexes
126 at the mesoscopic scale in order to bridge the gap between the microscopic and the
127 macroscopic scales, and to study their "collective" behavior in different biological conditions.
128 Here we report the use of these recently developed tools with the ability to export atomistic
129 models from rigid body ones, hinting at true multiscale capability, to build models of
130 individual full-length ECM proteins (*i.e.*, collagen IV, laminin-111, and nidogen-1) and
131 proteoglycan (perlecan) found in basement membranes, and to generate a molecular network
132 to build a three-dimensional model of a basement membrane-like ECM. Basement
133 membranes play a crucial role in delimiting tissue boundaries [27], as a filter in kidneys and
134 in tumor metastasis [28]. Our model will thus be of major interest to investigate the effects on

135 the organization of basement membrane of various biological contexts and diseases, which
136 could be mimicked by adding constraints to the model (e.g., changes in the number of a
137 particular molecule in a model to reflect up- or down-regulation of this molecule in diseases).

138 **MATERIAL AND METHODS**

139 **Unity 3D, a multi-platform game engine**

140 Game engines are suites of software and tools that let users import assets (3D objects, 2D
141 textures, game controller hardware interfaces...) in a unified environment to build simulations
142 for entertainment purposes (video games) or more serious applications (industrial training,
143 scientific visualization...) [29]. Unity3D is a multi-platform game engine, which could be
144 used by operating system agnostics and has been already used for scientific visualization [30].
145 It provides scripting tools that will be used both for simulation and programming interactions
146 between biomolecules in the same way video game characters interact with their environment
147 or with other characters. These scripts are embedded as components of each object in Unity
148 and program how these objects move or react in specific situations.

149

150 **Rigid body dynamics**

151 While in molecular dynamics, atoms position and velocity are updated at each time point
152 according to Newton's equation of motion, in rigid body dynamics, protein domains are
153 considered as rigid domains whose volumes never change or deform [22]. While particles
154 have three translational degrees of freedom, meaning that their motion can be described in
155 terms of x, y, z translation, rigid bodies add three rotational degrees of freedom around the x,
156 y and z-axis. To transform our all-atom structure gathered from the Protein Databank [31], we
157 simply apply the x,y,z, translation and rotation of the rigid body to the whole PDB file,
158 paving the way for getting from a rigid body representation back to an atomistic model as
159 described in the "Results" section. Simulations are run using physics engines which, like
160 other simulation tools (GROMACS, NAMD), are software packages that provide means to
161 simulate the behavior of physical systems within a given set of parameters/rules (force field).
162 In most physics engines rigid body dynamics is implemented using two components. One
163 holds the physics information used by the physics engine to update the simulation (mass,
164 position, orientation, velocities, forces), whereas the second, called a collider, holds the actual
165 spatial volume. Colliders are used to define the space occupied by a biomolecule as well as to
166 operate collisions between objects or the environment. Colliders are simple geometric shapes
167 (spheres, cylinders, cubes, planes) also called primitives, as this speeds up collision physics.
168 Complex mesh colliders exist but have significant computing costs. While rod-like helical or

169 fibrous molecules can be modelled as capsules or cylinders, more complex forms will require
170 a compound collider made of a mix of primitive colliders. It should be noted that several
171 figures of this article show detailed surface representations of the biomolecules, but this is, for
172 all intent and purpose, only as a visualization proxy for the physics entities (primitive
173 colliders) used in the simulation.

174 Chains of rigid bodies are created by articulating each rigid body with positional constraints,
175 preventing them to drift from one another. At each step of the simulation, rigid body positions
176 in the simulation are taken into account and constraints are applied to keep objects linked
177 together [32]. Positional constraints are also used to simulate interactions between molecules.
178 When two rigid body collide, the whole process is managed by a transient positional
179 constraint, which can be modified to be permanent or last a given amount of time that can be
180 modulated to mimick e.g., transient interactions or domain affinity. Random forces are
181 applied to the rigid bodies during the simulation. For this, a Langevin equation with a
182 viscosity term [33] is used. This mimics a fluid at thermal equilibrium and the viscosity term
183 allows for the solvent to be simulated without explicitly modelling the solvent molecules
184 individually (implicit solvation or continuum solvation), thus reducing the number of
185 objects/particles for which interactions must be calculated. Other programs such as
186 CellPACK [5] have made use of simplified representation like rigid bodies to create
187 macromolecular ensembles with a high packing ratio but the current version of CellPACK
188 does not seem to produce large-scale motion simulations. The data presented in this study
189 aims to demonstrate the potential of the DURABIN toolkit to help decipher ECM assembly
190 and dynamics.

191

192 **Membrane simulation**

193 A restraint field based on IMPALA (Integral Membrane Proteins and Lipids Association) [34]
194 was implemented in DURABIN to simulate how transmembrane helices anchor in the cell
195 membrane. This potential was used to simulate more realistic interactions between integrins
196 and the cell membrane in our model. This approach can be used for any type of
197 transmembrane component interacting with the ECM. The cell lipid membrane was described
198 as a continuum in the following function:

199

Equation 1:

200

$$C_z = 0.5 - \frac{1}{1 + e^{\alpha(|z| - z_0)}}$$

201

202 where z is the depth at which the helix collider is relative to the center of the membrane, z_0 the
203 depth at which $C_z = 0$. With α set to 1.99 and z_0 set to 15.75 Å, $C_z = 0.49$ at +/- 18 Å and $C_z =$
204 -0.49 at +/-13.5 Å. These values were chosen to represent the thickness of a 1,2-
205 dipalmitoylphosphatidylcholine (DPPC) bilayer in the fluid phase with a smooth transition to
206 the hydrophobic core of the membrane [34,35]. This thickness can be adapted to other lipids
207 or membrane compositions. A collider of 36 Å in height, spanning the whole “membrane”,
208 detects if a helix collider enters the “membrane” collider which applies a force proportional to
209 C_z pulling the transmembrane domain in the membrane. The result is a vector pointing toward
210 the inside of the membrane when the helix is in contact with the membrane but still in the
211 water phase and approaches 0 as the helix gets closer to the hydrophobic region of the
212 bilayer. Thus, any rigid body set in the simulation as being transmembrane, regardless of
213 shape, will be attracted inside the membrane *continuum* field, but will still be free to move
214 around once inside the membrane.

215

216 **Collecting or modeling 3D structures of interest**

217 Building an accurate model of multi-domains protein complexes requires the collection of the
218 highest number of structural data available. As mentioned above, many components of the
219 extracellular matrix are too large to have their 3D structure determined by X-ray or NMR as
220 full-length proteins. High-molecular weight proteins are indeed difficult to crystallize [36] or
221 to analyze by NMR [37]. Most 3D atomic structures available for ECM proteins or
222 proteoglycans are those of individual domains or pairs of domains and not those of full-length
223 molecules. Low-resolution techniques such as AFM, SAXS and rotary-shadowing electron
224 microscopy give insights into the domain organization of ECM proteins and their global size,
225 which are useful to build models. Although recent developments in the field of cryo-EM
226 increased the resolution, it is still costly [38] and subject to limitations (size of the complex,
227 among other things) [39]. Also of note, while recent, AI based techniques to solve the 3D
228 structure of proteins have made large contributions toward providing plausible structures of
229 previously unresolved or unresolvable structures [40,41], although one has to be aware of the
230 limitations of such technique especially regarding disordered regions [42]. Ideally, data
231 collected by both high- and low-resolution techniques should be combined to build our
232 models.

233 The main source of experimentally solved protein structures is the Protein Data Bank [43] but
234 data collected by cryo-electron microscopy are also available via the public repository
235 Electron Microscopy Data Bank [44][45]. When no 3D structure experimentally determined is

236 available, modelling approaches (e.g., threading, *ab initio* or homology modelling [46–48])
237 are used to predict the 3D structure of a protein or a domain from its primary sequence.

238

239 **3D structure importation and model building in Unity 3D**

240 The coordinates from the PDB being not centered, it is necessary to treat the PDB data so that
241 the center of mass corresponds to the origin of the coordinates using any tool allowing the
242 manipulation of 3D coordinates. Our approach uses Python scripts running in Blender
243 (<https://blender.org/>), a free and open-source 3D software that supports the modelling and
244 rendering of 3D objects, but any tool allowing the transformation of the coordinates of a PDB
245 file could be used. When an axis is obvious in the molecule (e.g., a rod-like triple-helical
246 domain), the main axis is aligned along the Y-axis which is by default the up direction in
247 Unity3D. The modified PDB file is then opened in VMD, where the molecular surface
248 representation is exported in Wavefront .obj file format. This file format is human readable
249 and can be used both by many applications including both Blender and Unity3D. The
250 molecular surface is used as a mesh representation for the underlying rigid bodies. VMD
251 produces very dense mesh, which can affect interactive rendering speed. Blender is used to
252 simplify the object, lowering the polygon count, while keeping the overall shape intact. Once
253 imported into Unity3D, the required components for the physics engine such as the rigid body
254 components themselves and the associated constraints are added.

255

256 **Simulating in Unity 3D**

257 We define a simulation box with a base area of 400 nm x 400 nm to fit the longest model of
258 the selected proteins. The thickness of the box varies with the nature of the studied system.
259 For example, the basement membrane thickness varies with age, disease and/or the methods
260 used to measure it. The thickness of basement membrane varies depending on tissues and on
261 the physiopathological context, but most basement membranes are 50–100 nm thick [49]. The
262 thickness thus was fixed at 100 nm, which in addition accomodates the length of laminin
263 molecules. The total size of the simulation box was 0.016 μm^3 including less than 600 rigid
264 bodies, all of them representing domains of larger macromolecules. In contrast, an atomistic
265 model of basement membrane made solely of integrin (one isoform), collagen IV (one
266 isoform), laminin and nidogen, would account for approximately 865 000 atoms.

267 While CGMD reduces the DOF of residues, the rigid body approach further reduces the DOF
268 of protein domains and represents large macromolecular complexes as articulated chains of

269 protein domains where individual domains are the beads of a very coarse model. This
270 approach has been used to study larger mesoscopic systems such as the yeast interphase
271 nucleus [33]. Using this approach, collagen IV was modelled as a chain of 44 rigid bodies
272 (one NC1 C-terminal domain and 43 triple-helical domains of 9-nm length and a total length
273 of ~390 nm [50]). Details on the constraints used to articulate the chain are given further in the
274 paper. The crystal structure of the collagen triple helix model [(Pro-Pro-Gly)₁₀]₃ (PDB 1K6F,
275 **Table 1**) was used as an individual triple-helical domain. This all-atom representation would
276 correspond to ~ 28 000 atoms (44*1K6F (528 atoms) + 1LI1(5253 atoms)). The number of
277 domains being far lower than the number of residues or atoms, the amount of computing
278 resources required is that of a desktop PC. It can even be run interactively, which allows the
279 addition of functionalities such as user feedback and interactions in real-time as the
280 simulation runs. By importing the model in the Unity3D game engine, it is possible to make a
281 representation of the collagen network running in real-time with few computing resources
282 [26].

283

284 **All-atom reconstruction: back-mapping**

285 In Unity3D, a C# script in the project's assets (SaveSnapshot.cs) exports the transformation
286 matrix of the rigid bodies from the molecule models in the ongoing simulation. The original
287 atomic coordinates are transformed using the matrix and the coordinates are saved as separate
288 files formatted as GROMACS .gro files. Because these are separate files, further work is
289 necessary to create one single molecule that can be used with a MD package like GROMACS.
290 But by loading all the separate .gro files in the visualization software VMD it is possible to
291 visualize the all-atom model, nonetheless.

292

293 **RESULTS**

294 **Building of rigid body models of individual proteins**

295 The 3D structures used to build the proteins of basement membrane models are listed in Table
296 1. There are for examples several structures of the NC1 domain of collagen IV issued from
297 different collagen IV species and isoforms (e.g., homo-oligomers or hetero-oligomers), cross-
298 linked or not, from different tissues, at various resolution. However, from a “rigid body”
299 point of view and at the mesoscopic scale, the NC1 domains are similar in term of general
300 shape (half-oval shaped geometry, same diameter, height). The 1LI1 structure has been

301 selected because it comprises two alpha1 chains and one alpha2 chains of collagen IV, which
302 corresponds to the major isoform of collagen IV in most tissues, and is cross-linked by the
303 Met-Lys cross-links. The crystal structure of the collagen triple helix model 1K6F, although
304 not specific to collagen IV, was used because the triple helix is a common feature of all
305 collagens [51]. A bacterial coiled-coil structure (2WPQ) was used to represent the coiled-coil
306 region of laminin-111 [52,53]. No 3D structure of the G1 domain of nidogen-1 was available,
307 and a threading approach was used to build a model of this domain [54]. Basement
308 membranes surround several cell types and several basement membrane constituents (e.g.,
309 laminin-111 and perlecan) interact with integrins. Integrins were thus included in the
310 simulation. 3FCS was first chosen because of its ability to interact with molecules such as
311 thrombospondins [55] in globular basement membrane, but as the focus of the project shifted
312 toward more general purpose simulation of the basement membrane, this integrin variant was
313 kept as the default integrin model because of the mechanical similarities of the ectodomain
314 between integrins. The extracellular part of the integrin, compared to other structures in *Table*
315 *I*, has all the domains solved in the same PDB file instead of being spread throughout the
316 PDB. To be exploitable in our simulation it was necessary to break down the extracellular
317 part of the integrin into domains to generate separate PDB files. The integrin α subunit for
318 example, is made of residues 1 to 452, the thigh (α subunit) goes from residue 453 to residue
319 604. The integrin β subunit was similarly sliced into domains [56].

Proteins	Domains	PDB entries
Collagen triple helix	Crystal Structure of the Collagen Triple Helix Model [(Pro-Pro-Gly) ₁₀] ₃	1K6F
Collagen IV	The hexameric noncollagenous domain 1 of human placenta collagen IV ($\alpha 1\alpha 1\alpha 2$ ισφφρλ)	1LI1
Laminin EGF-like modules	3 consecutive laminin-type EGF-like (LE) modules of laminin gamma1 chain harboring the nidogen binding site	1KLO
Laminin coiled-coil domain	A coiled-coil motif (Salmonella enterica SadA 479-519 fused to GCN4 adaptors)	2WPQ
Laminin ($\alpha 5$ chain)	Laminin $\alpha 5$ chain N-terminal fragment	2Y38
Laminin $\beta 1$ (short arm)	Laminin $\beta 1$ LN-LE1-4 structure	4AQS
Laminin $\gamma 1$ (short arm)	Laminin $\gamma 1$ LN-LE1-2 structure	4AQT
Laminin $\alpha 2$	laminin $\alpha 2$ subunit L4b Domain	4YEQ
Laminin $\alpha 1$ chain	Mouse laminin alpha1 chain, domains LG4-5	2JD4
Nidogen-1 (EGF domain)	EGF	1JL9
Nidogen	G1 threading model [54] (no available crystal structure)	
Nidogen-1 domain G2	Domain G2 of mouse nidogen-1	1H4U
Perlecan (LDL receptor)	2 nd repeat of the LDL receptor ligand-binding domain	1LDR

domain)	(domain mediates interactions of the receptor with two lipoprotein apoproteins, apo E and apo B-100)	
Perlecan (sea-urchin sperm protein, enterokinase and agrin domain)	SEA domain of human mucin 1	2ACM
Perlecan (LG like domain 3)	Laminin G like domain 3 from human perlecan	3SH4
Integrin ectodomain	Structure of complete ectodomain of integrin α IIB β 3	3FCS
Integrin transmembrane domain	Integrin α IIB β 3 transmembrane complex	2K9J
Complexes		PDB entries
Laminin-111 (integrin-binding domain)	The heterotrimeric integrin-binding region of laminin-111 (50 residues of α 1 β 1 γ 1 coiled coil and the first 3 laminin G-like (LG) domains of the α 1 chain)	5MC9
Laminin-Nidogen complex	Nidogen/Laminin Complex (a 6-bladed β -propeller domain in nidogen laminin epidermal-growth-factor-like (LE) modules III3-5)	1NPE
Perlecan/nidogen complex	Nidogen-1 G2/Perlecan IG3 Complex	1GL4

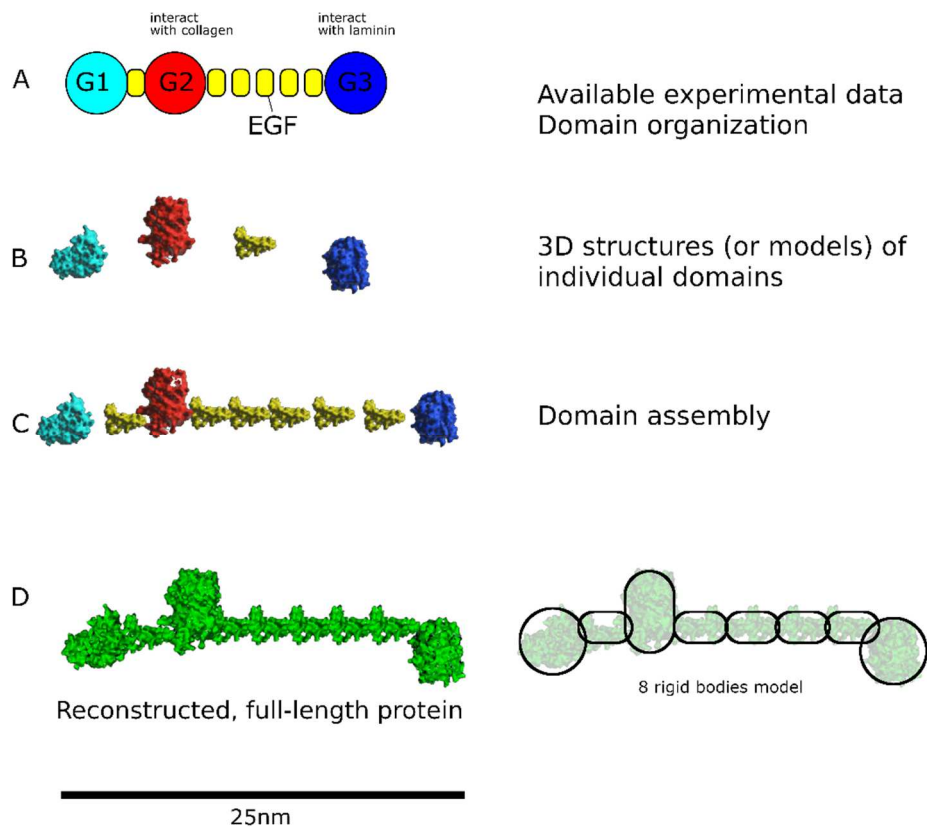
320 **Table 1: List of known PDB entries of proteins, glycosaminoglycans and protein**
321 **complexes of the basement membrane and integrins**

322 Known biomolecular interactions were integrated and parameterized for nidogen-1, where
323 two out of the three main domains, G2 and G3, interact with collagen IV and laminin-111
324 respectively [57]. Integrins interact with laminin-111 globular domain [58]. Collagen IV
325 dimerizes through its non-collagenous (NC1) C-terminal domain and the 7S N-terminal
326 domain to form a network [59]. Laminin-111 interacts with itself through the N-terminus of
327 α , β and γ chains [60]. Perlecan interacts with a wide range of ECM molecules and growth
328 factors. In basement membranes, perlecan connects laminin and collagen IV, while interacting
329 with integrin α 2 β 1 [61].

330

331 The process to go from existing data reported in the literature to a fully rigged rigid body
332 model that can be used in a rigid body simulation is summarized in Figure 1 using nidogen as
333 an example. The process is mainly manual, with helper scripts in Python for Blender and the
334 Editor functions for Unity3D. Although we reckon the task could be automated, this was not
335 the focus of this work. Nidogen-1 is a linear molecule made of three domains, G1, G2, G3
336 connected by EGF-like domains as represented in **Figure 1A**, based on biochemical [62] or
337 biophysical [63] data. If we assemble the structural bits according to the experimentally
338 determined domain organization the resulting s maximum size of nidogen is ~25 nm, roughly

339 the maximum particle size determined by SAXS experiments [63]. The curation of existing
340 data allowed us to determine the available structures and the part of the protein to be modelled
341 (*Table 1*). It should be noted that low-resolution data such as cryo-EM and SAXS envelopes
342 can be used for simulations, although *in fine* a true atomistic structure will be needed. The
343 domains were then converted to rigid body models with matching colliders as shown for G1
344 and G3 domains (**Figure 1D**). The slightly oblong EGF and G2 domains were matched with
345 capsule colliders (cylinder capped with spheres). The rigid bodies were assembled according
346 to the organization of domains by joining the C-terminus of a domain with the N-terminus of
347 the next domain. As explained in the passage on rigid body, joints are positional constraints
348 updated at each timesteps with customizable rotational degrees of freedom. Unity3D allows
349 for different presets of these constraints [64]. We used the configurable joints as it was the
350 most polyvalent and is highly configurable. The rotational and positional constraints between
351 rigid bodies were defined at this step to fine-tune flexibility by modulating rotational
352 constraints. In most cases, in absence of information on the rotational freedom between
353 domains, we use the simplest joint, positional constraint without rotational constraints. For
354 laminin and collagen domains, we add twist constraint, reflecting how super-coiled structures
355 can be more constrained in their helical axis, the reality being more complex [65].



356

357 **Figure 1: A rigid body model based on nidogen-1 for rigid body simulation.** A Domain
 358 structure of nidogen-1 including the G1, G2, G3 and EGF-like domains. B: Solvent
 359 Accessible Surface representation of the individual domains. C: Construction of the rigid
 360 body model based on literature data. D: final model used in the simulation, (right) schema of
 361 the rigid body colliders used in the simulation.

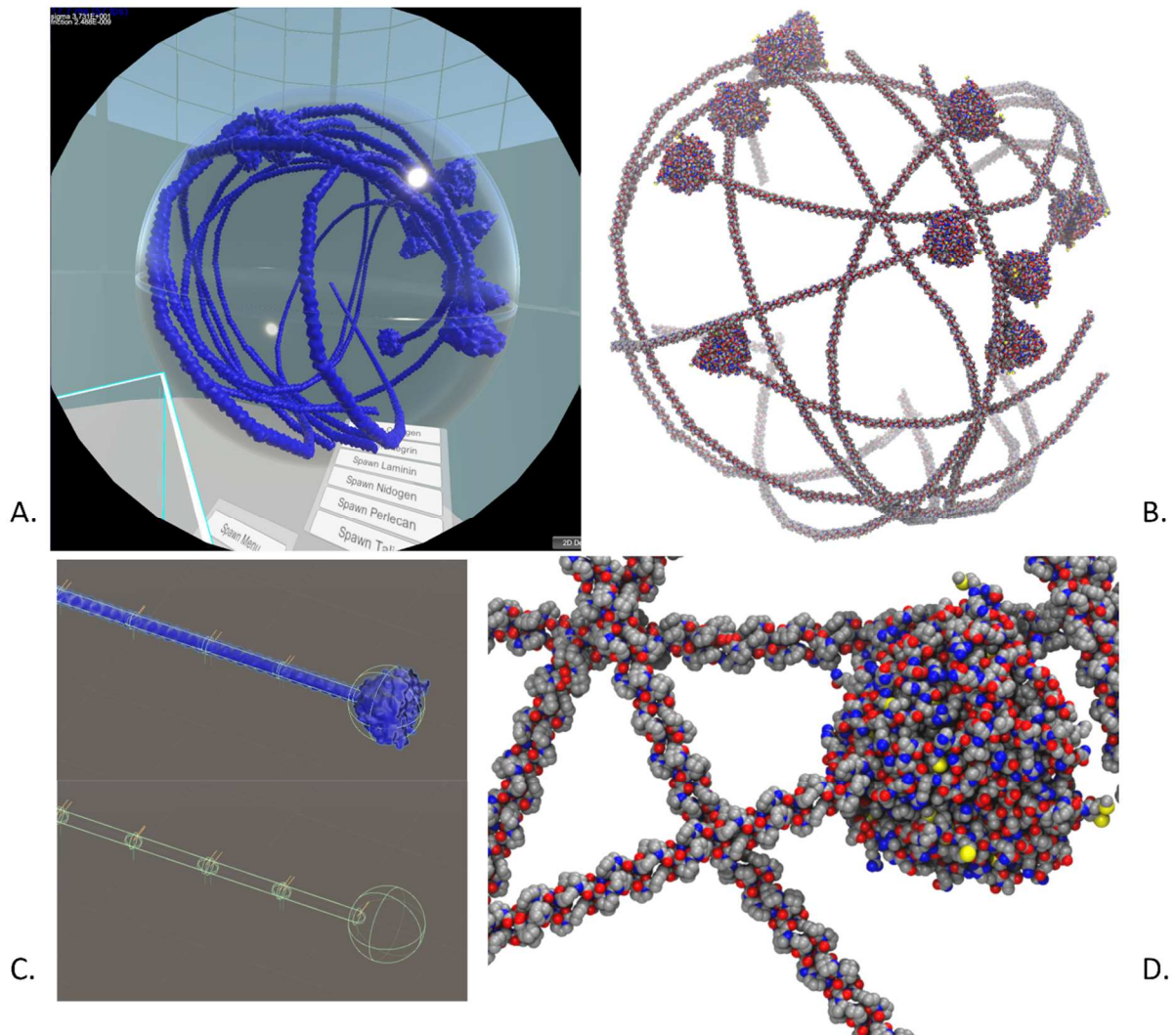
362

363 All-atom reconstruction

364 One of the goals of the DURABIN as a project is to develop convenient tools to do simulation
 365 from all atoms to rigid body and back to all atoms (called back-mapping in CGMD) in a true
 366 multiscale way. While rigid body dynamics can provide a convenient way to sample and
 367 study large-scale motions of molecular complexes, the details of biomolecular interactions lie
 368 in the all-atoms realms of small range motions and residue reorientation.

369 In **Figure 2**, we use custom scripts and user interaction to generate a couple of collagen IV
 370 molecules at 1/10th their final size and we then scale them back to their final real size. This
 371 allows us to fit long polymers in a very constrained spaces, like sphere, which does not have
 372 biological relevance for collagen IV but shows the ease of building all-atom models of a large
 373 protein in a very tightly confined space, which could be of practical use when modelling a
 374 crowded ECM or integrin trafficking [66]. In CGMD, the first step of back-mapping is to get

375 back the coordinates of the original atoms used to build the CG model, followed by an
 376 optimization step where the model is relaxed. In the case of rigid-body models, atomic
 377 coordinates are back-mapped to fit the newly oriented and positioned rigid body (**Figure 2B**).
 378 The minimization/relaxation step is far less trivial to achieve. It is a crucial phase for using
 379 the model in MD simulations, especially to correct problems such as atom superimposition
 380 and unwanted kinks.



381

382 **Figure 2: Example of atomistic model construction based on rigid body simulation.**
 383 Example of a complex model that can be made with DURABIN. A. Real-time rigid body
 384 models of the collagen-IV heterotrimer $\alpha1\alpha1\alpha2$ constrained to a sphere. B. Atomistic model
 385 built using PDB data (Table 1, 1K6F, 1LI1) and rigid bodies spatial orientation data extracted
 386 from A. C. Top: 3D mesh representation of the molecular surface (blue) lacking atomic
 387 details, overlaid or superimposed on the rigid bodies (green,). Bottom: rigid bodies alone
 388 showing how a slight overlap leads a gapless chain. D. Close up view of the all-atoms
 389 globular NC1 domain of collagen IV. Carbon: gray, oxygen: red, nitrogen: blue, Sulphur:
 390 yellow. Hydrogen atoms are not represented for the sake of clarity.
 391

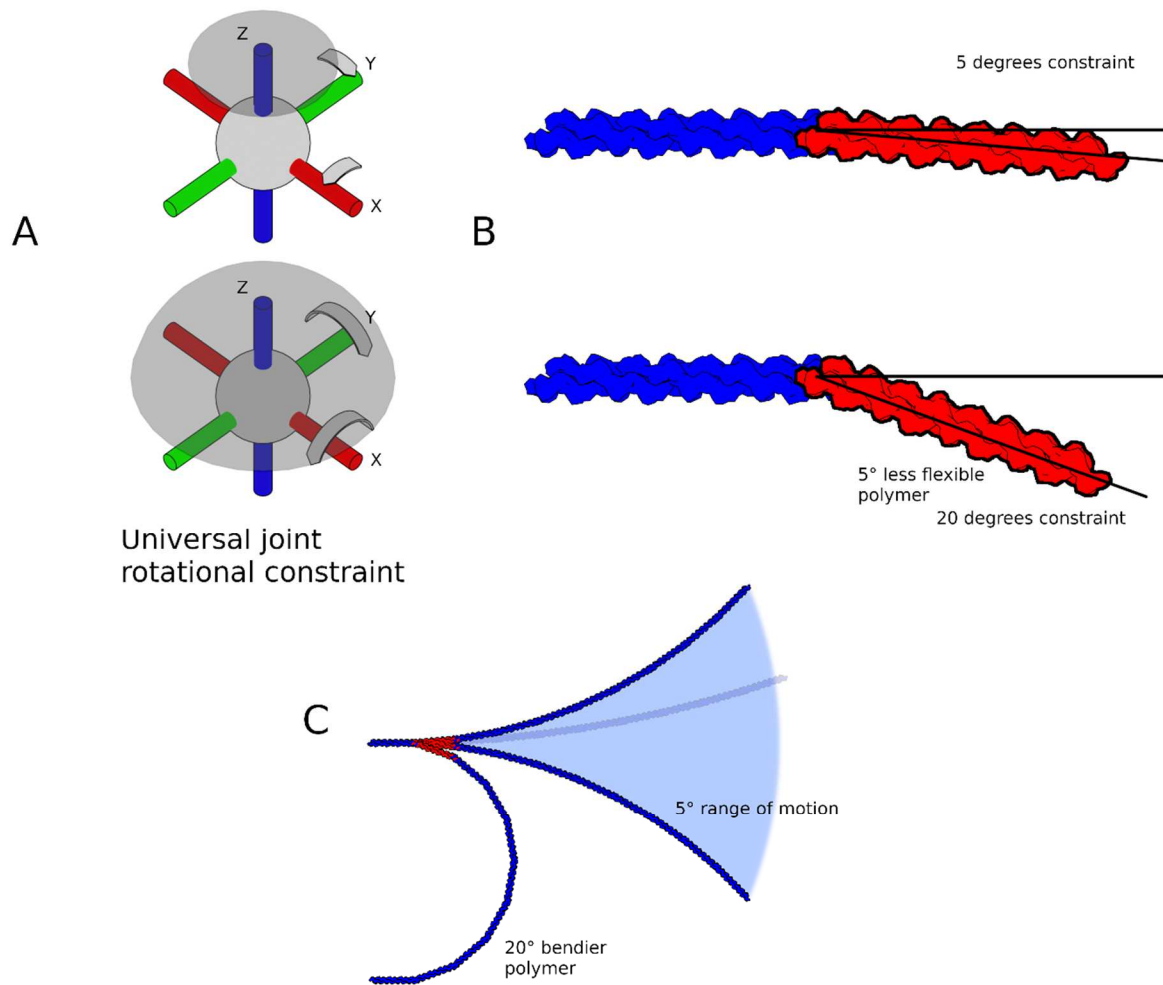
392 **Modelling a basement membrane**

393 *Setting up the simulation.*

394 Models of basement membrane components, namely collagen IV, laminin-111, nidogen-1 and
395 perlecan, were generated in a simulation box described in the Material and Methods section
396 (400 nm x 400 nm x 100 nm). While the components of the basement membrane are known,
397 the proportion of each component is still subject to debate [67]. In our model, we have chosen
398 a stoichiometry of 1:1 so that in theory, no molecule in our simulation is left orphaned during
399 self-assembly (one collagen interacting with one laminin and so on). The simulation was then
400 run, and the rigid body model allowed to diffuse in an implicit medium which viscosity is
401 modulated by the use of Langevin dynamics, under the influence of random thermal forces
402 linked to a thermostat (higher temperatures mean larger forces) in order to self-assemble into
403 a basement membrane-like ECM (Video Supplementary material). Any interactions at this
404 stage resulted from random/chance encounter during the simulation (Figure 5).

405 *Influence of collagen IV flexibility.*

406 In our previous study [26], we investigated the behaviour of laminins and nidogen. The
407 collagen IV chains contain 21–26 interruptions of various lengths in their triple helix [68],
408 which provide collagen IV molecules with flexibility. By tweaking the joint rotational
409 constraints (**Figure 3A**) between the 43 individual triple helical domains used to build the
410 model of collagen IV, it was possible to stiffen or loosen the collagen molecule (see **Figure**
411 **3B** and **Figure 3C**).



412

413 **Figure 3: Tweaking joint rotational constraint changes the flexibility of a polymer**
 414 **model.** A. How the rotation constraint affects the joint. X and Y axis is more limited in Top A
 415 than in Bottom A, the grey cap helps visualize the resulting Z axis exploration limits. B. Close
 416 up view isolating the rotation constraint. C. Difference in turn radius between a stiff (5
 417 degrees rotation constraint) and a bendy (20 degrees rotation constraint) polymer.

418

419 A simple simulation of the basement membrane showed the influence of collagen IV
 420 flexibility on the final structures formed (**Figure 5**). When collagen IV was rigid or
 421 moderately flexible, laminin and nidogen molecules tended to spread because the collagen
 422 rigidity helped to maintain a minimal distance (**Figure 5A** and **B**) and to form an irregular
 423 polygonal network during the simulation as previously observed experimentally [69].

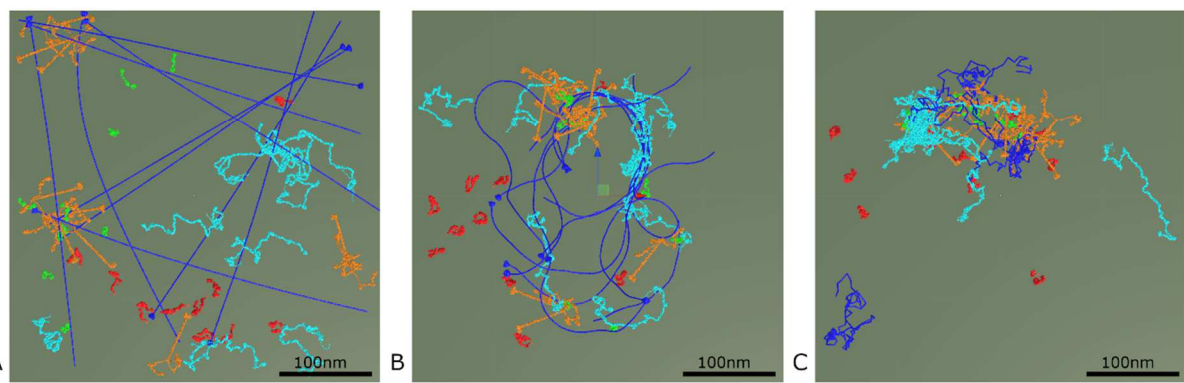
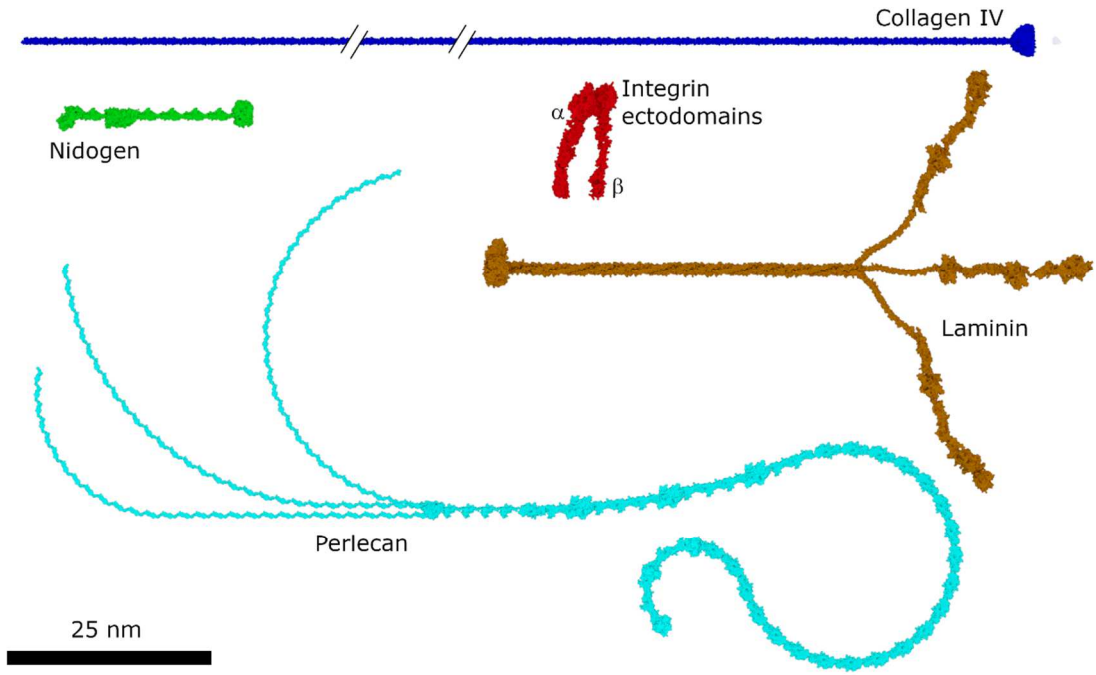
424

In contrast, when collagen IV was flexible, distances decreased, and the overall structure
 425 looked like an aggregate. If the flexibility was set to the maximum value, allowing the
 426 formation of kinks and U-turns, clumps formed, and the self-organization appeared to be lost.

427

Increasing the flexibility of the collagen IV model leads to the formation of a loose network

428 [69]. The ability to modulate the self-assembly of basement membrane from organized to
 429 disorganized networks could be useful to mimic what happens in some diseases and to
 430 investigate the underlying molecular events associated with and/or triggering the disease [70].
 431 The introduction of cross-links mimicking physiological cross-linked ECM would be useful
 432 to build an ECM model exhibiting various mechanical properties modulated by the extent of
 433 crosslinking [71].
 434



435
 436 **Figure 5:** Top, the main components of the basement membrane and integrins. Bottom A to
 437 C: Effect of increasing flexibility of the collagen IV model from the stiffest to most flexible
 438 molecule on the organization of the basement membrane during simulation
 439

440
 441 The proportions of each molecule in the basement membrane model are listed in Table 2 and
 442 compared to the Matrigel basement membrane composition [72].

	Matrigel [72]	Basement membrane model	Molecular weight of the basement membrane

			components
Laminin-111	60%	62.33%	900 kDa [73]
Collagen IV	30%	28.04%	405 kDa [74]
Nidogen	8%	9.63%	139 kDa [63]
			1444 kDa

443
444
445
446

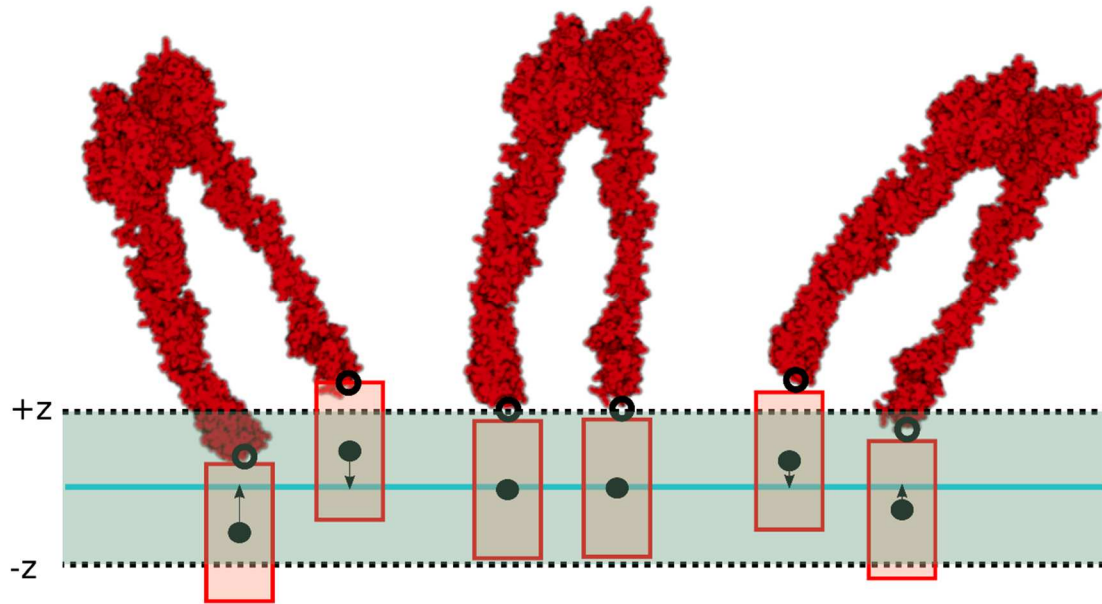
Table 2: Relative proportions calculated according to the molecular weight of the components of the Matrigel and the basement membrane model.

447 The numbers seem to support equal proportions between laminins, collagen and nidogen. The
448 model is based on a 1:1 ratio stoichiometry. This ratio was chosen in our model because it
449 maximizes networking and interactions while minimizing the number of molecules who
450 cannot find a partner to interact with. These proportions were similar to those of the basement
451 membrane extract Matrigel

452

453 **Membrane proteins: integrins**

454 Lipid bilayers and integrins are in close contact with basement membranes and define the
455 boundaries of our modelled and simulated system. Until now integrins were locked in a
456 separate 2D space with a rigid plane mimicking a membrane [26]. The constraints used did
457 not have a physical justification. We used here a restraint field, as described in the Material
458 and Methods section (membrane simulation), which can be used to simulate any
459 transmembrane molecules. Forces calculated from Equation 1, for instance, maintain the
460 transmembrane helix of the integrin models inside the simulated lipid bilayer (Figure 6). By
461 using this newly implemented restraint field, the integrins behave as we anticipated. The
462 restraint field is two sided, and while we only model the extracellular part, it will allow for
463 intracellular content to be simulated as well in the future.



464

465 **Figure 6: Integrin models embedded in a model of lipid bilayer.** The black dotted lines
 466 represent the boundaries of the lipid bilayer ($-z$, $+z$), and the cyan line corresponds to the
 467 center of the membrane bilayer. The rigid bodies representing the hydrophobic
 468 transmembrane helices are represented as red rectangles. The arrows represent the direction of
 469 C_z as a function of the position of the center of mass of the rigid bodies in the IMPALA field
 470 (a force-field specific to lipid membranes simplified as a *continuum*).

471

472 DISCUSSION

473 DURABIN was developed as a first contribution to fill the gap between microscopic and
 474 macroscopic observations. Experimental methods allowing the direct observation of
 475 biomolecular objects at the mesoscale are still lacking and simulation offers a tentative
 476 glimpse at systems that would otherwise elude us. We demonstrated that the combination of
 477 two incomplete datasets, namely the atomic details of microscopic observations of protein
 478 domains, with the global observation at the macroscopic scale is perfectly feasible for large
 479 molecular-weight protein. We have demonstrated that the tools we developed for DURABIN
 480 can simulate large motions in mesoscale systems like the basement membrane and hope it
 481 will help matrix biology researchers gain insight into the molecular structure of the basement
 482 membrane components at the atom level in a true multiscale fashion, all tools being simple to
 483 use and interactive thanks to virtual/augmented reality technologies.

484 Our rigid body to all-atom approach is promising but could certainly be improved. While
485 transforming atomic coordinates using rigid body positions and rotations works, joining the
486 heterogeneous bits before doing some minimization/optimisation on the resulting atomic
487 model remains challenging. This two-stage approach is already commonly used in CGMD
488 and the “Backward” back-mapping tool [75]. It uses a geometrical reconstruction approach
489 starting from the backbone and library of geometrical rules. Our rigid body approach allows
490 us to populate simulation with multiple copies of the rigid body model of the components of
491 the basement membrane, but we plan to improve this approach. One of these improvements
492 could come from position-based physics or particle-based rigid bodies. It is a recent
493 development where rigid bodies are defined not by collider primitives but by a set of strongly
494 constrained particles allowing for arbitrary shapes and unlocking computing parallelism [76].
495 This opens the possibility to perform simulations with a higher population of models in the
496 simulation box. The N- terminal arms of the α , β and γ chains of different laminin molecules
497 interact to form a laminin network [77,78]. This was indeed the case during the simulation of
498 our model but the short arms of the β and γ chains belonging to the same were also able to
499 interact. This could be prevented in the future by making the short arms of the β and γ chains
500 rigid enough so that the β and γ arms of the same laminin molecule never come in contact.
501 This is another strength of the DURABIN approach. The rigid body models are easy to
502 modify and adapt to the ever-changing large amount of research information available. The
503 more information we get, the more accurate the simulation will be. It would be interesting to
504 use DURABIN to test if and how the modifications of the basement membrane composition
505 affect molecule diffusion, and basement membrane stability and physical properties,
506 mimicking physio-pathological changes occurring *in vivo*. The model reported here is the first
507 step towards the building of an extracellular matrix mesoscope, which will provide the
508 opportunity to investigate molecular functions of the ECM and the biological processes it is
509 involved in.

510 Basement membranes are usually associated with cells through interactions with adhesion
511 receptors, sulfated glycolipids and others. We have not yet included in our model the
512 interactions between basement membrane components and glycolipids, or dystroglycan which
513 should provide new insights on the role of cell surface receptors in basement membrane self-
514 assembly. Furthermore, the polarization of proteins in the basement membrane should also be
515 considered. For example, the C-terminal globular domains of laminins interact with the cell
516 surface, whereas the N-terminus of their three chains form the laminin network in the

517 basement membrane [79]. Collagen XVIII also has a polarized orientation in basement
518 membranes with the N-terminus facing the fibrillar matrix and the C-terminus orientated
519 towards the plasma membrane [80]. Last, collagen IV C-terminus dimerization was
520 implemented, but we still have to fully model the tetramerization of the 7S domain, which is
521 much more complex since it involves 12 chains, is cross-linked by lysyl oxidase like-2 but is
522 currently modelled as a simple constraint.

523 Biomolecular non-covalent intermolecular bonds are not programmed to dissociate during the
524 simulation, meaning that they are stable once created. The challenge is to find a way to
525 translate values of the equilibrium dissociation constants into a programmable parameter in
526 the simulation. This could be expressed as a contact frequency defining the probability a non-
527 covalent bond/interaction could form or dissociate at each timestep.

528 Our approach developed with the Unity platform benefits from the native support of haptic
529 and augmented/virtual reality (AR/VR) devices. The advantage of VR is that it makes easier
530 for non-expert users to navigate the computer environment. From simply walking around the
531 visualization to quite literally grabbing the model and turning it around, it offers very intuitive
532 and new means of looking at molecular models [81,82]. Unity also provides real-time visual
533 feedback to the user. DURABIN provides an easy way to apprehend visual medium for the
534 users to observe and interact with complex mesoscale systems, but DURABIN lacks
535 advanced molecular representation features like ribbons or cartoon representation, unlike
536 Unitymol [30] or other visualization software such as VMD or PyMOL. DURABIN provides
537 tools to import, simulate, manipulate, and export molecular models, but it does not aim at
538 performing all-atom MD and at replacing well-known MD packages such as Gromacs,
539 NAMD, Amber or LAMMPS. DURABIN speeds up the study of large molecular systems at
540 the mesoscale level by facilitating the building and sampling of complex molecular systems
541 such as ECM large multi-domains molecules.

542

543 **ACKNOWLEDGEMENTS**

544 This work was supported by Grand Reims (France) via the Chaire MAgICS (Modélisation
545 moléculaire et Agroressources: Ingrédients, Cosmétique et Santé) to MD.

546

547 **AUTHORS CONTRIBUTION**

548 **HW:** methodology, software, formal analysis, investigation, data curation, visualization,
549 writing – original draft. **JM:** writing - review & editing. **MD:** conceptualization, writing -
550 review & editing, supervision, funding acquisition. **SRB:** writing - review & editing. **SB:**

551 writing - review & editing, supervision. **NB**: conceptualization, writing - review & editing,
552 resources, project administration, funding acquisition.

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